

Water Use Dynamics of Peach Trees under Postharvest Deficit Irrigation

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Abstract

Postharvest deficit irrigation is a potential strategy for conserving valuable fresh water for production of early season tree fruit crops such as peaches. However, water use dynamics under deficit irrigation conditions that can be described as seasonal changes in crop evapotranspiration (ET_c) and crop coefficient (K_c) are largely unknown. A three-year field study was carried out in a 1.6 ha peach orchard to determine seasonal ET_c and K_c characteristics. The orchard was divided equally into 72 plots, in which 12 randomly selected plots received deficit irrigation and the remaining 60 plots received full irrigation. A Bowen ratio flux tower was installed in the orchard to make meteorological measurements for estimating an integrated ET_c for the orchard. The study showed that from July to August 75-85% of the daily net radiation was used by latent heat or partitioned into ET_c . The average monthly cumulative ET_c was 151 mm in June, 162 mm in July, and 155 mm in August. K_c values under deficit irrigation conditions or termed as Deficit_ K_c was computed as ratios of the ET_c over potential evapotranspiration or ET_o , and were compared with K_c derived from a lysimeter study under non-water stressed conditions or termed as Lysimeter_ K_c . The maximum Deficit_ K_c values were 0.90, 1.03, and 1.07 for the three field seasons but all were smaller than 1.20, the maximum Lysimeter_ K_c . The study demonstrated that water stress under deficit irrigation can be characterized in K_c values. The approach may be used to detect if portions of an orchard or the entire orchard are under water stress. Conversely, the method may provide guidance on deploying deficit irrigation practices with pre-determined Deficit_ K_c .

Keywords: Bowen ratio, Potential evapotranspiration, *Prunus persica* L., Water stress

1. Introduction

The recent episodic and wide-spread drought in the United States highlights the importance of reliable fresh water supplies for agricultural production especially in the arid and semi-arid regions such as the Central Valley of California. Although total farmed land area in California decreased from 11.75 million ha in 1992 to 10.25 million ha in 2010, irrigated agricultural land area increased from 3.08 million ha in 1992 to 3.24 million ha in 2010 (Klonsky, 2012). Moreover, during the eight year time span farm lands cropped with orchards increased from 0.89 to 1.13 million ha because of the high cash values and consumer demands. Among the significant land areas for orchard crops about 23,000 ha are peaches primarily grown in the Central Valley of California. Like in all other orchard crops, growing peaches in the Valley depends on irrigation to meet crop water demand by the peach trees.

For early ripening varieties of peaches, e.g. harvested in late May to early June, deficit irrigation may be used to reduce water use during the postharvest non-fruit bearing periods, e.g. June to August when the crop water demand is the highest. From 1992 to 2010, the annual total amount of potential evapotranspiration required for the area ranges from 1200 to 1400 mm and the peak water use periods of June to August three month totals averaged 582 mm, which accounts for approximately 45% of the annual crop water use (CIMIS, 2013). Therefore there is great potential for adopting water saving technologies such as deficit irrigation during the non-fruit bearing summer months. Also, perennial crops such as fruit trees are suitable candidates for applying deficit irrigation strategies because of deeper and more extensive root systems than most annual crops (Costa et al., 2007; Fereres and Soriano, 2007; Girón et al., 2015). Various studies have been reported with respect to physiological and yield responses of peach trees using deficit irrigation and indicated substantial water savings without significantly impacting the yield and fruit quality (Chalmers et al., 1981; Johnson et al., 1992; Goldhamer et al., 1999; Girona et al., 2005; Falagán et al., 2015).

To practice deficit irrigation, it is important to know the actual crop water needs, which can be determined as crop evapotranspiration (ET_c) or the amount of water needed to replenish water lost by ET_c . Determination of ET_c can be done with direct field measurement using in-situ weighing lysimeters (Dugas et al., 1985; Howell et al., 1985; Johnson et al., 1992); micrometeorological energy balance approaches such as the Bowen ratio method (Fuchs and Tanner, 1970; Angus and Watts, 1984; Heilman et al., 1994; Teixeira et al., 2007), the eddy covariance method (Baldocchi, 1988; Testi et al., 2004; Paco et al., 2006), and the surface renewal method (Paw et al., 1995; Castellvi and Snyder, 2009); or the FAO crop coefficient (K_c) method, e.g. multiplying theoretical potential evapotranspiration or ET_o with a plant-dependent crop coefficient (K_c) value to determine ET_c for a particular crop at a particular growth stage (Doorenbos and Pruitt, 1977; Allen et al., 1998). Once a reasonable estimate is made on ET_c , the challenge is to determine how much deficit to use and methods of monitoring plant water status without over stressing the plants. One approach for choosing deficit is to pre-select a fraction of ET_c as the irrigation target, such as replenishing only 50% ET_c using irrigation water. Other possibilities include taking a fraction of K_c , especially during peak water use periods such as in the summer months (June – August) for peach trees. This would be another way of implementing deficit irrigation and reducing irrigation amounts

needed for essential physiological needs but not fully meeting the crop ET_c requirement.

The objective of this study was to characterize water use or ET_c and K_c dynamics of a peach orchard in a three year field experiment when the orchard was managed under postharvest deficit irrigation. Irrigation decisions were based on ET_c estimates using real time ET_o and literature K_c values derived from an earlier lysimeter study. Because only portions of the orchard received deficit irrigation and majority received full irrigation, the overall orchard-wide ET_c was estimated with an approximate Bowen ratio method with instrument tower installed in the orchard downwind from the dominant wind direction. An orchard-wide K_c was determined to reflect the effect of deficit irrigation.

2. Materials and Methods

2.1 Field Description and Deficit Irrigation Treatment

Field studies were carried out from 2008 to 2010 in a 1.6 ha mature peach orchard located near Parlier, California, USA. The trees were early-ripening “Crimson Lady” (*Prunus persica* (L.) Batsch) on “Nemaguard” rootstock planted in April 1999 (Bryla et al., 2005). Each year, the peaches were harvested in late May to early June. The dimension of the orchard was 122 m in the east – west direction and 133 m in the north –south direction, with individual trees spaced 1.8 m apart within rows (in the north-south direction) and 4.9 m between rows (in the east-west direction). The orchard was laid out for irrigation studies using furrow, drip, and micro-sprinkler irrigation systems and equally divided into 72 irrigation plots with each plot consisted of 24 trees in three rows with eight trees per row per plot (Figure 1). A border row and a border tree in each row were used on each side or end of the orchard. The soil at the field site is a Hanford sandy loam soil (coarse-loamy, mixed, thermic Typic Xerorthents).

During the three year field experiment, 12 out of the 72 irrigation plots received postharvest deficit irrigation and the remaining 60 plots received full irrigation (Figure 1). The deficit irrigation treatment plots included 6 furrow irrigation plots and 6 drip irrigation plots to replace a portion of the crop evapotranspiration (ET_c). For the furrow deficit irrigation, a watering event was initiated when stem water potential approached -2 MPa. For the drip deficit irrigation, only one fourth of the full amount of ET_c was applied during each irrigation event. To guide irrigation decisions, the values of daily ET_c were determined by multiplying real-time values of potential evapotranspiration (ET_o) with literature crop coefficients (Lysimeter_ K_c or Lys_ K_c) developed for the same peach variety from an adjacent orchard using a large underground weighing lysimeter (Johnson et al., 2005).

2.2 Meteorological and Energy Balance Measurements

To provide on-site ET_c estimates, a modified Bowen ratio system was deployed in the orchard. Because the predominant wind was from the northwest direction, the system tower was installed near the southeast corner of the orchard approximately 138 m downwind from the northwest corner of the orchard (Figure 1). Also because the tree heights can increase significantly during each year, a telescoping pole of 5.1-cm diameter galvanized steel pipe fitted in a 7.6-cm diameter steel pipe as the base was installed within a tree row to minimize interferences with orchard management, e.g. annual pruning, chemical spray, etc.

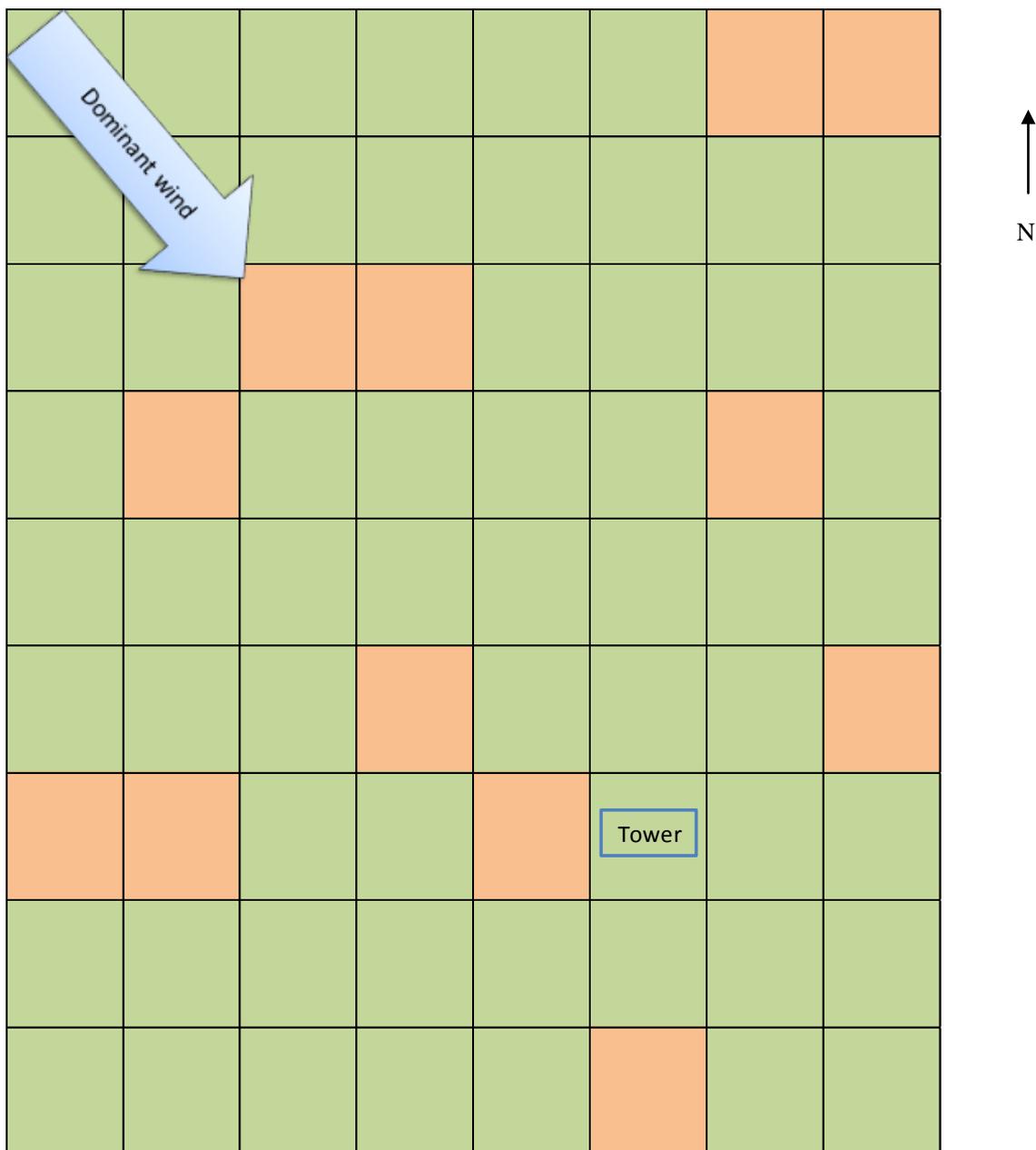


Figure 1. Schematic of peach orchard lay-out (Green = nondeficit irrigation; Orange = deficit irrigation), tower location, and dominant wind direction. Orchard dimension = 122 m (east-west) by 133 m (north-south)

Sensors were mounted on two 1.9-cm diameter aluminum cross beams on the telescoping pole, placed at two heights separated by 2 m distance: the lower beam at canopy level, upper beam at 2 m above the canopy. The pole was raised periodically during each growing season to maintain the lower beam within ± 15 cm of the top of the average canopy height.

The tower site consisted of a set of meteorological and soil sensors for energy balance measurements. Sensors mounted on the upper beam included a LI-COR silicon pyranometer

for solar radiation (LI200X, Campbell Scientific, Inc., Logan, UT¹), a net radiometer for net radiation (Q*7, Radiation and Energy Balance Systems, Seattle, WA), an air temperature and relative humidity sensor (Vaisala HMP 45C, Campbell Scientific, Inc., Logan, UT), and an R.M. Young Wind speed and direction sensor (model 05103, Campbell Scientific, Inc., Logan, UT). Sensors mounted on the lower beam included an air temperature and relative humidity sensor (Vaisala HMP 45C, Campbell Scientific, Inc., Logan, UT) and a Met One wind speed and direction set (model 034B, Campbell Scientific, Inc., Logan, UT).

To account for partial ground shading from the tree canopy, the soil heat flux was measured with three heat flux plates (HFT3, Radiation and Energy Balance Systems, Seattle, WA), all buried at 1 cm depth: the first one located in the tree row half way between two adjacent trees, the second one located half way between two adjacent tree rows, the third one was at half distance between the first and second plates. An arithmetic average from the three plates was used to represent the soil heat flux in energy balance calculations. In addition to the heat flux measurement, six type T copper - constantan thermocouples were installed at the tower site for soil temperature measurements. They were located at the same relative distances to the tree and tree rows as the heat flux plates (but 10 cm away from the plates), three were installed at 1 cm depth and three at 10 cm depth, and an average temperature was used for each soil depth. A thermocouple was also installed in the tree canopy at 1 m above ground to monitor within canopy air temperature.

A datalogger (model CR23X, Campbell Scientific, Inc., Logan, UT) was used to record sensor measurements at 1 Hz then averaged to 5-min readings in 2008 and 15-min average readings in 2009 and 2010. Sensor readings were monitored daily to weekly for quality control and repair for possible sensor malfunction. At the beginning of each season, all sensors and their installation were rechecked for accuracy in readings and physical installation.

2.3 Evapotranspiration and Crop Coefficient Calculations

Based on the net radiation (R_n), soil heat flux (G), and air temperature (T_a) and relative humidity (h_r) measurements, latent energy (LE or λE) available for evapotranspiration in the peach orchard was estimated using the Bowen ratio method:

$$\lambda E = \frac{R_n - G}{1 + BR} \quad (1)$$

where BR is the Bowen ratio which was computed from:

$$BR = \gamma \frac{T_a^l - T_a^u}{e_a^l - e_a^u} \quad (2)$$

¹ Mention of trade names or commercial products in this publication is solely for the purpose of providing specific information and does not imply recommendation or endorsement by the U.S. Department of Agriculture.

where γ is apparent psychrometer constant ($0.0662 \text{ kPa } ^\circ\text{C}^{-1}$, Monteith and Unsworth, 1990); T_a^l , T_a^u , e_a^l and e_a^u are respectively air temperature and apparent vapor pressure measured at lower and upper beams above the canopy. As recommended by Foken et al. (1997) for ensuring sufficient wind turbulence, instantaneous BR calculations for wind speed differences $< 0.3 \text{ m s}^{-1}$ were excluded from BR calculations. Also the latent heat calculation would be undefined when $\text{BR} = -1$, therefore all BR values between -0.75 and -1.25 were also excluded, as suggested by Ohmura (1982). To fill the gaps from excluded BR values, 30-min moving-windows averages were applied and used for latent heat calculations.

The vapor pressure (e_a^l and e_a^u) was calculated from relative humidity and air temperature using the Tetens formula (Buck, 1981):

$$e_a^{l,u} = h_r^{l,u} \left[a \exp \left(\frac{bT_a^{l,u}}{T_a^{l,u} + c} \right) \right] \quad (3)$$

where coefficients used in the saturation vapor pressure function were $a = 0.611 \text{ kPa}$, $b = 17.502$, and $c = 240.97 \text{ } ^\circ\text{C}$ (Campbell and Norman, 1998). Bowen ratio method ET_c was calculated by converting latent heat to depth of water.

To estimate peach water use from the FAO crop coefficient method, potential ET or ET_o was calculated using the modified Penman-Monteith equation (Campbell and Norman, 1998):

$$\text{ET}_o = \frac{s(R_n - G) + \gamma \lambda g_v D_v / p_a}{s + \gamma} \quad (4)$$

where parameter s is slope of the saturation model fraction at apparent atmospheric pressure (p_a), λ is latent heat of vaporization of water (44 kJ mol^{-1}), g_v is total vapor conductance of the canopy, and D_v is vapor pressure deficit. Parameters s and D_v were determined using measurements of T_a and h_r and the Tetens formula for saturation vapor pressure:

$$s = \frac{abc}{p_a (c + T_a)^2} \exp \left(\frac{bT_a}{c + T_a} \right) \quad (5)$$

$$D_v = a (1 - h_r) \exp \left(\frac{bT_a}{c + T_a} \right) \quad (6)$$

where T_a and h_r from the upper beam were used in the calculations, and parameters a , b , c were the same as in equation (3).

Total vapor conductance of the canopy (g_v) was computed from stomatal conductance (g_s)

and boundary layer aerodynamic conductance (g_a) using the following:

$$g_v = \frac{1}{\frac{1}{g_s} + \frac{1}{g_a}} \quad (7)$$

where g_s was assumed constant at $300 \text{ mmol m}^{-2} \text{ s}^{-1}$ for non-water stressed peach trees (Correia et al., 1997). The aerodynamic conductance depends on meteorological and boundary layer properties including wind speed and temperature gradient at the crop surface. The average June-August wind speed from 2008-2010 was 0.95 m s^{-1} (Table 1) and average difference between the canopy temperature and air temperature was $-2 \text{ }^\circ\text{C}$ (Wang and Gartung, 2010). This produced an average g_a value of $250 \text{ mmol m}^{-2} \text{ s}^{-1}$ (Campbell and Norman, 1998). Thus an estimated average g_v of $136 \text{ mmol m}^{-2} \text{ s}^{-1}$ was used for ET_o calculations for the three year field experiment.

For energy partition assessment, the sensible heat (H) component was also estimated using the Bowen ratio equation (Foken, 2008):

$$H = (R_n - G) \frac{BR}{1 + BR} \quad (8)$$

Because a portion of the orchard was under post-harvest deficit irrigation, the composite effect would be reductions in ET_c from full irrigation ET . This effect could be reflected as a stressed K_c or a deficit K_c , and it was calculated as Bowen ratio ET_c divided by ET_o .

3. Results and Discussion

3.1 Meteorological Conditions during the Experiment

For the postharvest months of June to August of 2009, as an example, daily air temperature in the peach orchard was found in the range of 10 to $15 \text{ }^\circ\text{C}$ for daily minimum to approximately 30 to $40 \text{ }^\circ\text{C}$ for daily maximum (Figure 2). From late June to end of August, air temperature inside the canopy at 1 m above ground was consistently lower than temperature at canopy top or 2 m above the canopy. Daily maximum at 2 m above the canopy was 1 - 2 degrees higher than temperature at the canopy top. The same trend was observed in 2008 and 2010, and as expected the monthly average air temperature was consistently the highest at 2 m above the canopy and the lowest at 1 m above ground inside the canopy (Table 1). Also air temperatures in June and August of 2008 were generally higher than temperatures observed in respective months in 2009 and 2010.

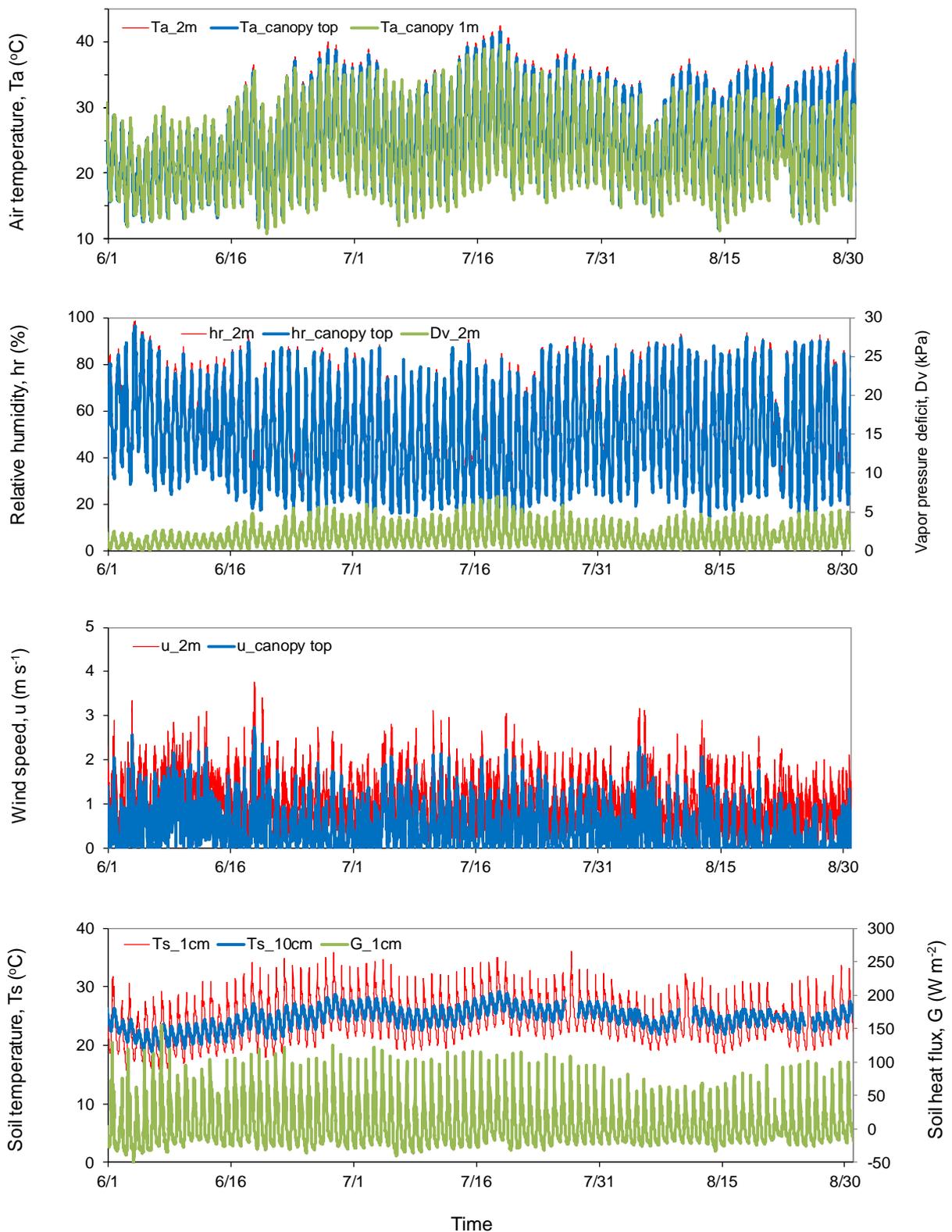


Figure 2. Real time meteorological variables measured in 2009 at the tower site in a peach orchard, Parlier, CA

Table 1. Monthly average meteorological variables measured from 2008 to 2010 during postharvest deficit irrigation treatment in a peach orchard, Parlier, CA

Month	Parameter †	2008	2009	2010
June	T _a (°C), 2 m above canopy	24.8	23.3	23.9
	T _a (°C), at canopy top	24.0	22.9	23.6
	T _a (°C), 1 m above ground	23.3	22.3	23.1
	h _r (%), 2 m above canopy	44.7	55.0	50.5
	h _r (%), at canopy top	45.6	51.7	45.7
	D _v (kPa), 2 m above canopy	2.07	1.55	1.71
	u (m s ⁻¹), 2 m above canopy	1.30	1.31	1.70
	u (m s ⁻¹), at canopy top	0.71	0.58	1.32
	T _s (°C), 1 cm depth	24.9	23.5	24.6
	T _s (°C), 10 cm depth	24.5	23.4	24.1
	G (W m ⁻²), 1 cm depth	8.93	5.49	6.75
July	T _a (°C), 2 m above canopy	27.3	27.7	26.9
	T _a (°C), at canopy top	26.5	27.0	26.5
	T _a (°C), 1 m above ground	25.4	25.4	NA ‡
	h _r (%), 2 m above canopy	52.0	48.2	54.8
	h _r (%), at canopy top	51.3	45.6	49.7
	D _v (kPa), 2 m above canopy	2.03	2.29	1.89
	u (m s ⁻¹), 2 m above canopy	1.20	1.23	1.25
	u (m s ⁻¹), at canopy top	0.62	0.47	0.73
	T _s (°C), 1 cm depth	27.7	25.6	26.9
	T _s (°C), 10 cm depth	26.3	25.9	27.8
	G (W m ⁻²), 1 cm depth	4.88	3.78	4.24
August	T _a (°C), 2 m above canopy	27.0	25.7	24.8
	T _a (°C), at canopy top	26.3	25.0	24.3
	T _a (°C), 1 m above ground	24.5	22.8	21.6
	h _r (%), 2 m above canopy	50.4	53.7	56.9
	h _r (%), at canopy top	49.8	51.4	52.2
	D _v (kPa), 2 m above canopy	2.10	1.85	1.68
	u (m s ⁻¹), 2 m above canopy	1.07	1.10	1.16
	u (m s ⁻¹), at canopy top	0.46	0.32	0.60
	T _s (°C), 1 cm depth	25.9	24.0	23.2
	T _s (°C), 10 cm depth	25.1	24.6	24.9
	G (W m ⁻²), 1 cm depth	2.75	2.60	3.96

† T_a = air temperature, h_r = relative humidity, D_v = vapor pressure deficit, u = wind speed, T_s = soil temperature, G = soil heat flux; ‡ NA = data not available.

Responding to diurnal temperature fluctuations and vapor density changes, for the months of June to August 2009 relative humidity ranged from approximately 20-30% for daily lows to 80-90% for daily highs (Figure 2). Monthly averages ranged from 45 to 55% for the three year period during the study (Table 1). For potential evapotranspiration calculations, vapor pressure deficit was computed at 2 m above the canopy and the values in 2009 generally ranged from 0 to 5 kPa (Figure 2). Monthly averages of vapor pressure deficit were from 1.6 to 2.3 kPa during the three year experiment (Table 1). Similar to air temperature observations, relatively higher vapor pressure deficit values were found for June and August of 2008 than that in respective months of 2009 and 2010 (Table 1).

Measured wind speed during the three month period was relatively low where the daily maximum was generally less than 3 m s^{-1} (Figure 2). As expected, wind speed at 2 m above the canopy was consistently higher than that at the canopy level and the monthly average wind speed from June to August of 2008 to 2010 was $1.1\text{-}1.7 \text{ m s}^{-1}$ at 2 m above the canopy and $0.3\text{-}1.3 \text{ m s}^{-1}$ at the canopy level (Table 2).

Soil temperature at 1 cm depth fluctuated diurnally from upper teens to low 30 °C whereas temperature at 10 cm depth was at low to mid 20 °C (Figure 2). Monthly average temperature ranged from 23 to 28 °C for the three year experiment (Table 1). Higher soil temperature was found in the month of July (26-28 °C) than in June or August (23-26 °C). Soil heat flux also showed strong diurnal variations reaching a daily maximum of approximately 125 W m^{-2} (Figure 2). As expected, the monthly average heat flux decreased from $5.5\text{-}8.9 \text{ W m}^{-2}$ in June to $3.8\text{-}4.9 \text{ W m}^{-2}$ in July to $2.6\text{-}4.0 \text{ W m}^{-2}$ in August (Table 1).

Although 2008 appeared to be a warmer year than 2009 and 2010, in general, these meteorological parameters found during the three year period were within the limit of long term averages for the area (CIMIS, 2013).

3.2 Bowen Ratio Data Quality Control and Energy Partition

Figure 3 shows the 30-min moving windows averages of 5-min cumulative ET_c in 2008, as an example, for before (a) and after (b) data quality control by excluding conditions when wind speed difference $< 0.3 \text{ m s}^{-1}$ (Foken et al., 1997) or $-1.25 < \beta < -0.75$ (Ohmura, 1982). Clearly, the data quality control procedures removed the unreasonably artificial high ET_c values caused by the inherent limitations of the Bowen ratio method. The same data quality control procedure was applied to the entire dataset from the three year field study. The basis of the Bowen ratio method assumes that the ratio of the gradients of temperature and humidity between two heights behaves similarly to the ratio of the sensible to the latent heat flux (Dugas et al., 1991). However, both the sensible and latent heat flux do not explicitly consider wind speed differences at the two heights or differences between the measurement heights. Larger differences between the measurement heights would most likely increase the differences in measured air temperature and humidity, hence making the Bowen ratio method more robust. Local or regional meteorological characteristics can also add needed requirements for deployment of the Bowen ratio method. Places with more frequent low wind speed or mixing conditions for turbulence likely require larger height separation than areas

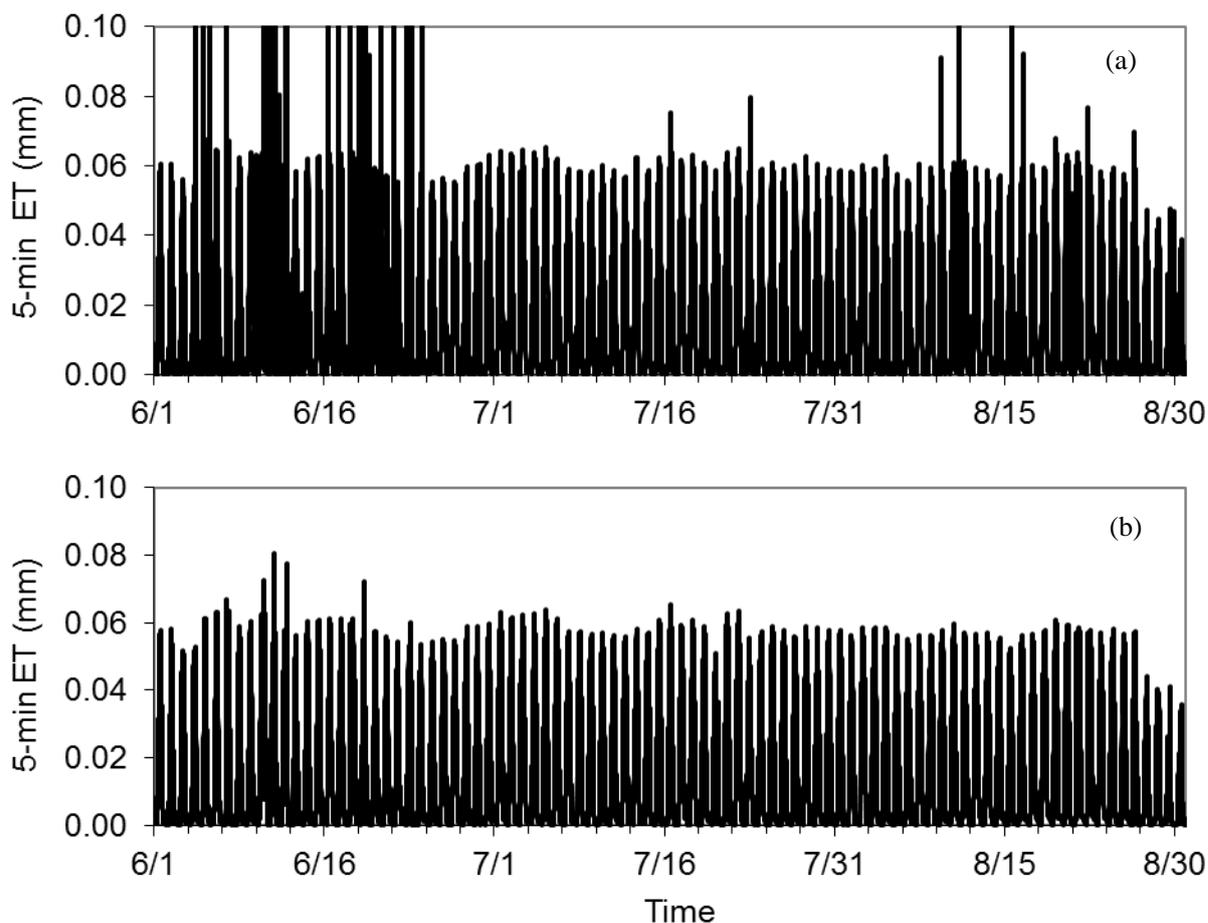


Figure 3. Real time 2008 crop evapotranspiration or ET before (a) and after (b) data quality control by excluding conditions when wind speed difference $< 0.3 \text{ m s}^{-1}$ (Foken et al., 1997) or $-1.25 < < -0.75$ (Ohmura, 1982) and taking 30-min moving windows averages of 5-min cumulative ET measurements

frequently see strong wind turbulence. Logistic considerations, however, often limit the height separation, especially for perennial tall plants such as trees and vines in that the lower measurement height also needs to be at or above the canopy top. Teixeira et al. (2008) used 3-m height above a mango tree canopy for the upper beam measurement of a Bowen ratio system and Heilman et al. (1994) placed the sensors at 1-m above a vineyard canopy. The 2-m height separation used in this study was a compromise between accuracy and logistical feasibility. With this height and the 138 m distance upwind to the field edge, the fetch-to-height ratio would be 69:1 which was well above the minimum requirement for Bowen ratio measurements.

To illustrate energy partition, one day from July to August or the peak evaporative periods was randomly selected for each of the three years of field measurements (Figure 4). As shown in the figure, 75-85% of the daily R_n was used by latent heat (LE), 25-13% by sensible heat,

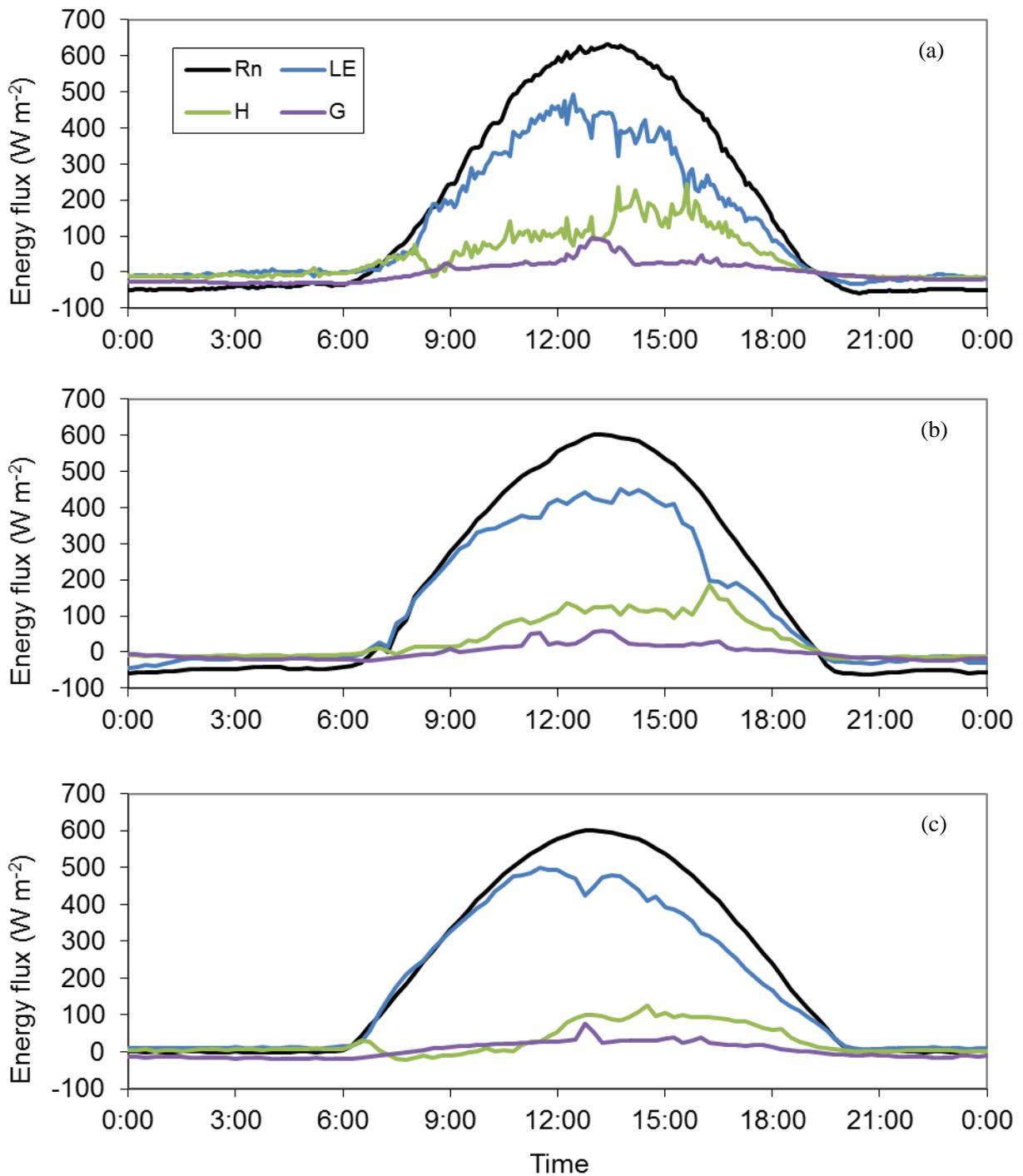


Figure 4. Diurnal energy fluxes of net radiation Rn, latent heat LE, sensible heat H, and soil heat G for (a) 29 July 2008, (b) 14 August 2009, and (c) 19 July 2010

and nearly a net zero usage for soil heat flux. Similar energy partitions were observed in a mature mango orchard (LE = 80-85% Rn; Teixeira et al., 2008), in a young olive orchard (approximately 70%; Testi et al., 2004), and in both wine and table grape vineyards (88%; Teixeira et al., 2007). The relatively low sensible heat was unique to the area where surface boundary layer is often under stable conditions with light winds especially in the mornings

(Castellvi and Snyder, 2009; CIMIS, 2013). Convective conditions tend to start in the afternoon after receiving solar heating in the morning. The dominant wind pattern will be different if experiencing an incoming storm system but it is rare for the area during the summer growing months. The small net soil heat flux was attributed to low exposure of bare soil. Independent canopy cover measurements with a TetraCam camera showed approximately 90% ground canopy cover during the months of June – August in this orchard.

3.3 Comparison of Crop Coefficients and Evapotranspiration

Actual crop coefficients (K_c) under postharvest deficit irrigation, thereafter termed Deficit_ K_c , were computed as ratios of ET_c estimated from the Bowen ratio method over ET_o (Figure 5). For comparison purposes, the time-dependent linear relationship developed for the same peach variety from a field site under fully irrigated conditions and in close proximity to this study site (Johnson et al., 2005) was used to calculate the “potential” crop coefficients, thereafter termed Lysimeter_ K_c . It is worth to note that the Lysimeter_ K_c increased linearly until day of year (DOY) 187 or July 6 then remained constant at 1.20. As shown in the figures, Deficit_ K_c values were consistently lower than Lysimeter_ K_c in 2008 starting in early June. In 2009 and 2010, Deficit_ K_c values were similar to Lysimeter_ K_c until July when it became slightly lower than Lysimeter_ K_c . Discrepancies in Deficit_ K_c and Lysimeter_ K_c between 2008 and the following two years were likely attributed to the higher temperatures occurred in 2008 than in 2009 or 2010. The generally lower values of Deficit_ K_c in all three years, compared to the Lysimeter_ K_c values, were attributed to the deficit irrigation treatments in the orchard. The average reduced (from 1.20) maximum crop coefficient, by the deficit irrigation treatments, was 0.90, 1.03, and 1.07 for 2008, 2009, and 2010, respectively. Rather than DOY 187, as in the full irrigation lysimeter study, the time for reaching the maximum Deficit_ K_c was DOY 158 in 2008 (06/08/2008), DOY 168 in 2009 (06/17/2009), and DOY 172 in 2010 (06/21/2010), respectively. These findings indicated that after the onset of deficit irrigation treatment in early June, overall crop water use started to decrease and reached a “stressed” equilibrium maximum value sooner than the typical DOY 187 date and at values lower than 1.20 should all the trees be fully irrigated. Also, only 17% of the orchard was deficit irrigated. Should the entire orchard be managed under deficit irrigation, smaller Deficit_ K_c values would be expected.

As shown in Figure 6, comparisons were made in estimated ET_c using Lysimeter_ K_c , Deficit_ K_c , and Bowen ratio values for each year. As expected, the ET_c values estimated from Lysimeter_ K_c was higher or overly estimated than that using the Deficit K_c for most of the postharvest periods: early June to end of August in 2008, late June to end of August in 2009, and July to August in 2010. ET_c values determined using the Deficit_ K_c were virtually the same as the direct Bowen ratio estimates. It is important to note the interdependence of determination of Deficit_ K_c on Bowen ratio estimates of ET_c . The merit with using a deficit

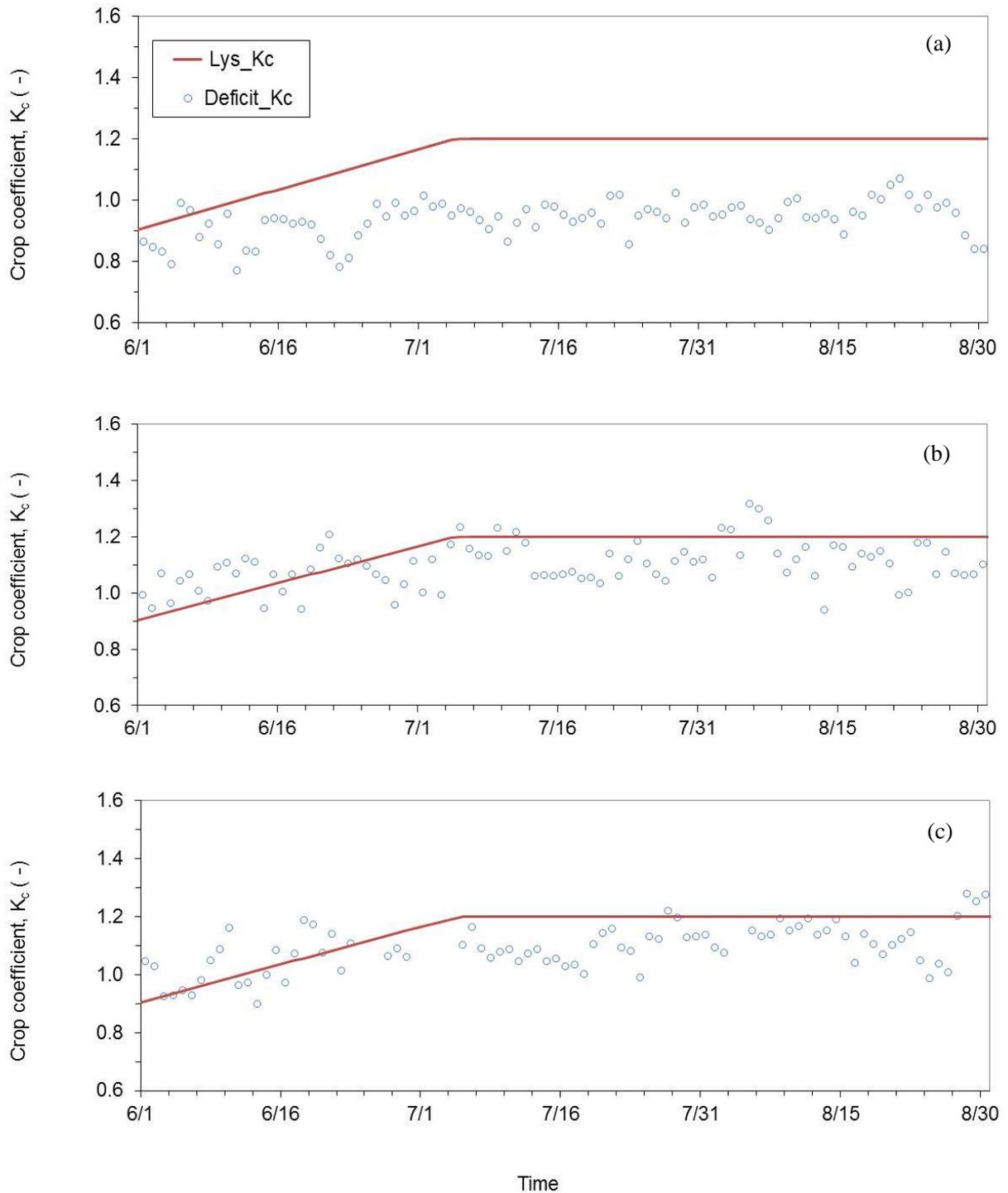


Figure 5. Daily crop coefficients of peach orchard under postharvest deficit irrigation in (a) 2008, (b) 2009, and (c) 2010. Lysimeter_Kc or Lys_Kc = crop coefficient from lysimeter measurement under full irrigation (Johnson et al., 2005). Deficit_Kc = crop coefficient computed from potential ET (ET_o) and actual ET (ET_c) from Bowen ratio measurement

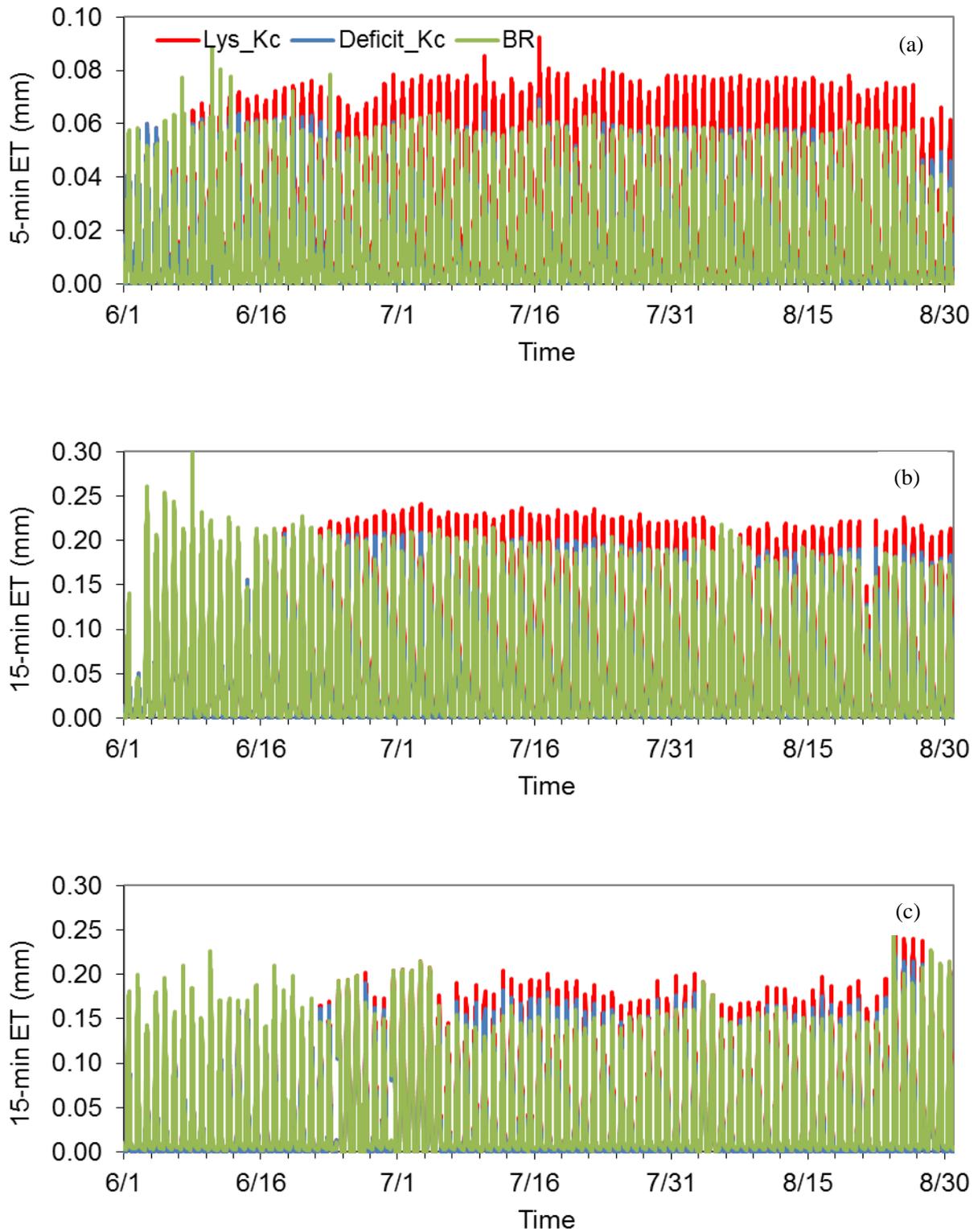


Figure 6. Comparison of real time ET_c using the Lysimeter_K_c, Deficit_K_c, and the Bowen ratio (BR) methods for (a) 2008, (b) 2009, and (c) 2010

K_c is the simple analogy to the FAO 56 method of using K_c to manage irrigation scheduling, should a known or predetermined deficit is given. To further illustrate the improvement of Deficit_ K_c on ET_c assessment, diurnal 5-min or 15-min ET_c values were compared for the dates when K_c reached the maximum K_c (i.e., 06/08/2008, 06/17/2009, 06/21/2010) with that of July 31 of respective years (Figure 7). As can be seen in the figures, the three methods of ET_c estimates were similar up to reaching the respective maximum deficit K_c values. ET_c values on July 31 clearly showed over-prediction using the lysimeter K_c , especially during middle part of the day. This is virtually caused the larger value for the multiplier (i.e. 1.20) than the reduced maximum Deficit K_c (i.e., 0.90, 1.03, and 1.07 for 2008, 2009, and 2010 respectively). Using the lysimeter K_c values up to reaching the maximum Deficit K_c , then using the constant Deficit K_c , monthly cumulative ET_c was calculated and compared with cumulative ET_c estimated using the lysimeter_ K_c and Bowen ratio methods for the three years (Table 2). Cumulative ET_c in June showed variable differences between the three methods because the onset of deficit irrigation likely had different initial impact on crop water use. In July and August, the Lysimeter K_c method consistently over-predicted cumulative ET_c compared to the Deficit_ K_c and the Bowen ratio methods. The results also indicated that if Deficit K_c can be determined or pre-selected, then the well-established FAO 56 method for ET_c (Allen et al., 1998) may be used for deficit irrigation management. The other way to describe water stress under deficit irrigation is to use a crop coefficient stress factor, e.g. K_s , as proposed in Allen (2000) and adopted in Suleiman et al. (2007) for deficit irrigation of cotton. For this study, the K_s factor would be the ratio of maximum deficit K_c over 1.20 or 0.75, 0.86, and 0.89 for 2008, 2009, and 2010, respectively. For times before reaching the maximum K_c , the K_s factor would be one.

The reason for a reduced maximum K_c in deficit irrigation management where crops are under some degree of water stress is generally believed to be caused by stomatal regulation or reduced stomatal conductance under these conditions. The challenge is how to estimate the degree of stress or deviation of K_c from non-stressed conditions or basal K_c (K_{cb}) values. Some recent approaches explored using thermal images from satellite (e.g., the METRIC model by Allen et al., 2007) or unmanned aerial vehicles (UAVs, e.g., Zarco-Tejada et al., 2012) to make water stress assessment. The merit with thermal images is the ability to detect spatial variations in canopy temperature to infer water status or water stress caused by soil variability or by variations in irrigation distribution uniformity. Under deficit irrigation, all plants are under some water stress and spatial variability can make certain areas in an orchard over-stressed to levels that might cause physiologically irreversible damages to the trees (Fereres and Soriano, 2007). Therefore, the selection of levels of irrigation deficit in terms of a deficit K_c value or a similar benchmark irrigation level with respect to ET_o should consider the potential spatial variability of water availability on a farm scale to minimize risks on crop losses. In other words, some safety factor should be used in choosing a deficit K_c for deficit irrigation. This study, in an inverse way, clearly demonstrated that water stress under deficit irrigation treatment can be characterized in K_c or so defined as Deficit_ K_c . If values of Deficit_ K_c can be pre-determined, the approach may be used to provide guidance on deploying deficit irrigation practices.

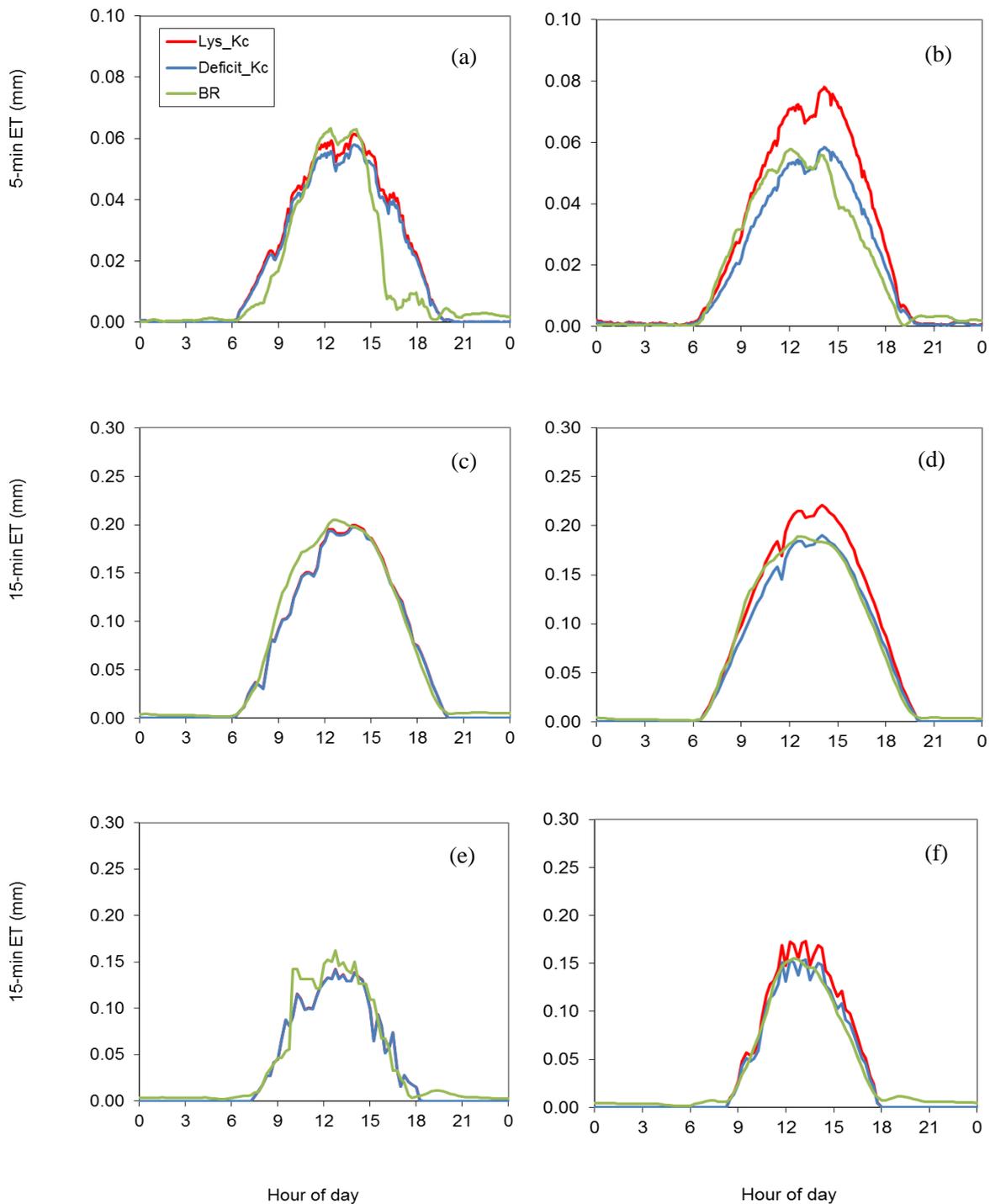


Figure 7. Comparison of real time ET_c using lysimeter K_c, deficit K_c, and Bowen ratio (BR) measurement for (a) 8 June 2008, (b) 31 July 2008, (c) 17 June 2009, (d) 31 July 2009, (e) 21 June 2010, and (f) 31 July 2010

Table 2. Monthly cumulative crop evapotranspiration (ET_c) in 2008, 2009, and 2010 in a peach orchard received postharvest deficit irrigation in 12 randomly distributed plots from a total of 72 plots (Figure 1)

Month	Method †	Cumulative ET_c (mm)		
		2008	2009	2010
June	Lysimeter K_c	177.7	165.8	113.2
	Deficit K_c	155.7	160.0	111.3
	Bowen ratio	136.0	186.6	129.7
July	Lysimeter K_c	216.2	228.2	140.3
	Deficit K_c	162.3	196.5	125.6
	Bowen ratio	162.4	194.4	129.0
August	Lysimeter K_c	201.7	197.2	142.0
	Deficit K_c	151.3	169.3	126.6
	Bowen ratio	151.5	175.6	136.5

† Lysimeter K_c method was product of potential evapotranspiration (ET_o) and lysimeter crop coefficient (Johnson et al., 2005). Deficit K_c method was product of ET_o and deficit K_c , i.e. correcting for deficit irrigation effect on maximum crop coefficient $K_c \leq 0.90$ (2008), ≤ 1.03 (2009), ≤ 1.07 (2010). Bowen ratio method ET_c was direct conversion of total monthly latent heat to water depth.

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